15-213

Concurrent Programming November 28, 2007

Topics

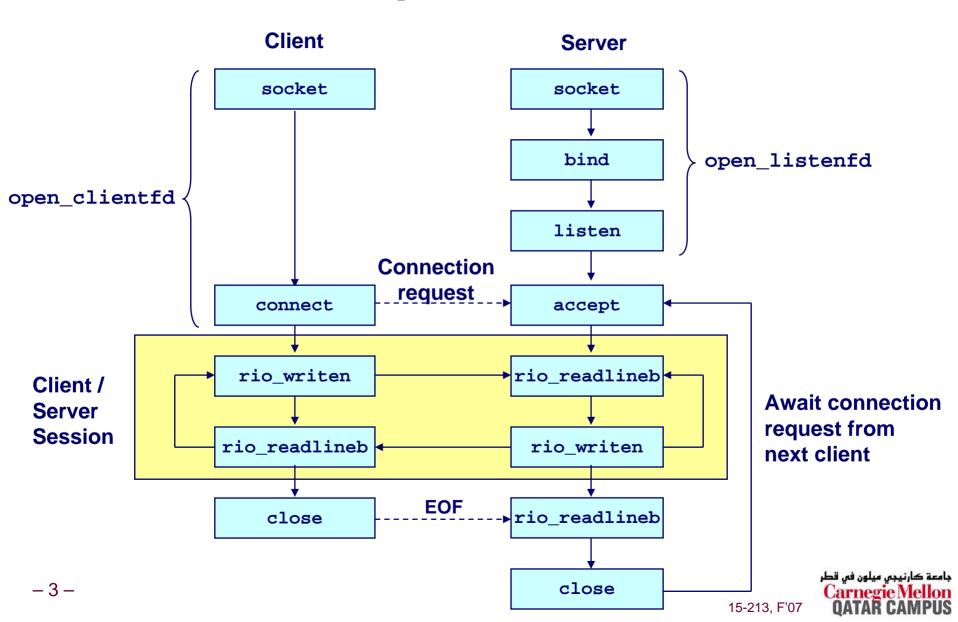
- Limitations of iterative servers
- Process-based concurrent servers
- Event-based concurrent servers
- Threads-based concurrent servers



Concurrent Programming is Hard!

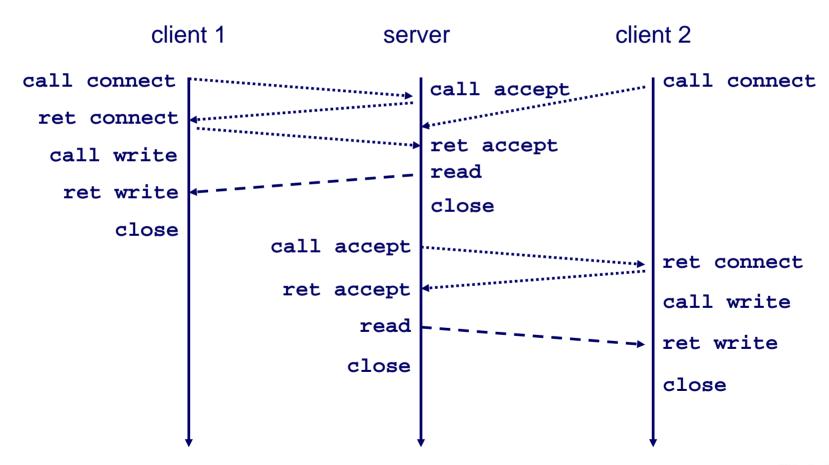
- The human mind tends to be sequential
- The notion of time is often misleading
- Thinking about all possible sequences of events in a computer system is at least error prone and frequently impossible
- Classical problem classes of concurrent programs:
 - Races: outcome depends on arbitrary scheduling decisions elsewhere in the system
 - Example: who gets the last seat on the airplane?
 - Deadlock: improper resource allocation prevents forward progress
 - Example: traffic gridlock
 - Lifelock / Starvation / Fairness: external events and/or system scheduling decisions can prevent sub-task progress
 - Example: people always jump in front of you in line
- Many aspects of concurrent programming are beyond the scope of 15-213

Echo Server Operation

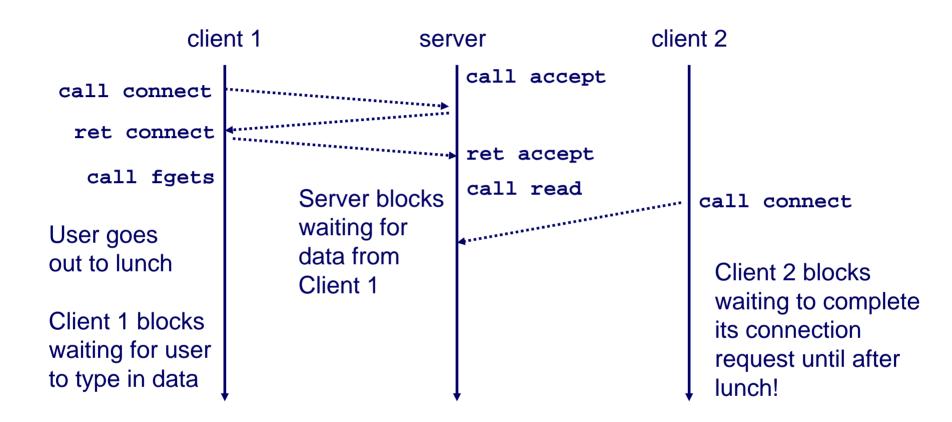


Iterative Servers

Iterative servers process one request at a time.



Fundamental Flaw of Iterative Servers

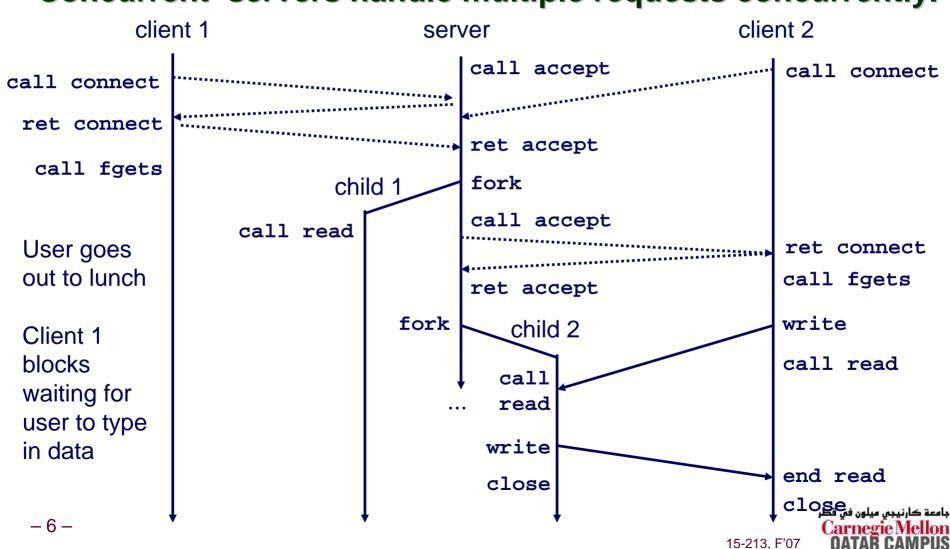


Solution: use concurrent servers instead.

■ Concurrent servers use multiple concurrent flows to serve multiple clients at the same time.

Concurrent Servers: Multiple Processes

Concurrent servers handle multiple requests concurrently.



Three Basic Mechanisms for Creating Concurrent Flows

1. Processes

- Kernel automatically interleaves multiple logical flows.
- Each flow has its own private address space.

2. Threads

- Kernel automatically interleaves multiple logical flows.
- Each flow shares the same address space.

3. I/O multiplexing with select()

- User manually interleaves multiple logical flows.
- Each flow shares the same address space.
- Popular for high-performance server designs.

Review: Sequential Server

```
int main(int argc, char **argv)
    int listenfd, connfd;
    int port = atoi(argv[1]);
    struct sockaddr in clientaddr;
    int clientlen = sizeof(clientaddr);
    listenfd = Open listenfd(port);
   while (1) {
       connfd = Accept(listenfd, (SA *)&clientaddr, &clientlen);
       echo(connfd);
       Close(connfd);
    exit(0);
```

- Accept a connection request
- Handle echo requests until client terminates

Inner Echo Loop

```
void echo(int connfd)
{
    size_t n;
    char buf[MAXLINE];
    rio_t rio;

    Rio_readinitb(&rio, connfd);
    while((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
        printf("server received %d bytes\n", n);
        Rio_writen(connfd, buf, n);
    }
}
```

- Server reads lines of text
- Echos them right back

Echo Server: accept Illustrated



1. Server blocks in accept, waiting for connection request on listening descriptor listenfd.



2. Client makes connection request by calling and blocking in connect.



3. Server returns connfd from accept. Client returns from connect. Connection is now established between clientfd and connfd.

Process-Based Concurrent Server

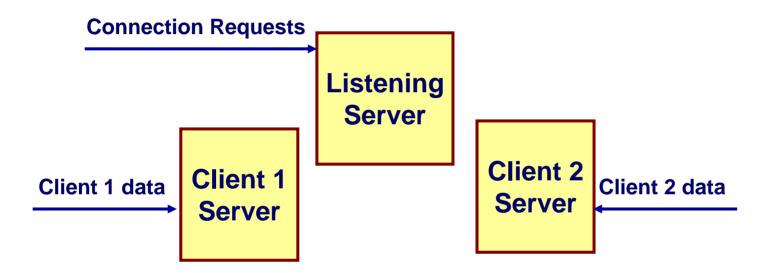
```
int main(int argc, char **argv)
                                          Fork separate process for each
    int listenfd, connfd;
                                            client
    int port = atoi(argv[1]);
                                          Does not allow any
    struct sockaddr in clientaddr;
                                            communication between
    int clientlen=sizeof(clientaddr);
                                            different client handlers
    Signal(SIGCHLD, sigchld handler);
    listenfd = Open listenfd(port);
   while (1) {
       connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
       if (Fork() == 0) {
           Close(listenfd); /* Child closes its listening socket */
           echo(connfd); /* Child services client */
           Close(connfd); /* Child closes connection with client */
                            /* Child exits */
           exit(0);
       Close(connfd); /* Parent closes connected socket (important!) */
```

Process-Based Concurrent Server (cont)

```
void sigchld_handler(int sig)
{
    while (waitpid(-1, 0, WNOHANG) > 0)
    ;
    return;
}
```

Reap all zombie children

Process Execution Model



- Each client handled by independent process
- No shared state between them
- When child created, each have copies of listenfd and connfd
 - Parent must close connfd, child must close listenfd



Implementation Issues With Process-Based Designs

Server must reap zombie children

to avoid fatal memory leak.

Server must close its copy of connfd.

- Kernel keeps reference for each socket.
- After fork, refcnt(connfd) = 2.
- Connection will not be closed until refcnt(connfd)=0.

Pros and Cons of Process-Based Designs

- + Handles multiple connections concurrently
- + Clean sharing model
 - descriptors (no)
 - file tables (yes)
 - global variables (no)
- + Simple and straightforward.
- Additional overhead for process control.
- Nontrivial to share data between processes.
 - Requires IPC (interprocess communication) mechanisms FIFO's (named pipes), System V shared memory and semaphores

Traditional View of a Process

Process = process context + code, data, and stack

Process context

Program context:

Data registers

Condition codes

Stack pointer (SP)

Program counter (PC)

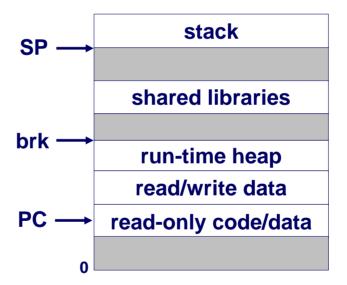
Kernel context:

VM structures

Descriptor table

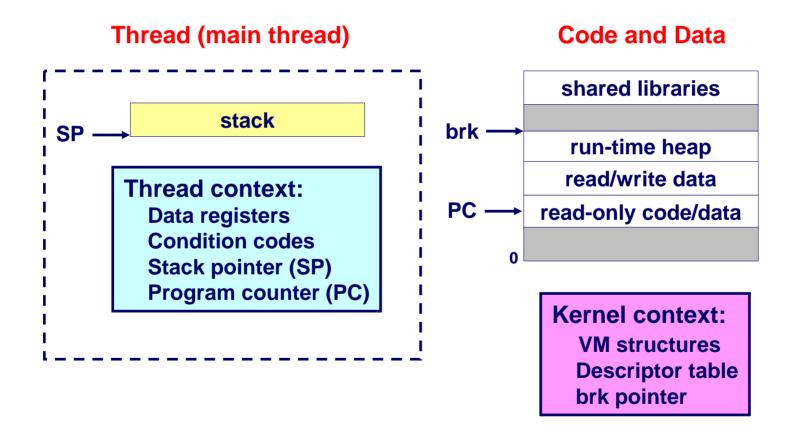
brk pointer

Code, data, and stack



Alternate View of a Process

Process = thread + code, data, and kernel context



A Process With Multiple Threads

Multiple threads can be associated with a process

- Each thread has its own logical control flow
- Each thread shares the same code, data, and kernel context
 - Share common virtual address space
- Each thread has its own thread id (TID)

Thread 1 (main thread)

Shared code and data

Thread 2 (peer thread)

stack 1

Thread 1 context:
Data registers
Condition codes
SP1
PC1

run-time heap
read/write data
read-only code/data

Kernel context:
VM structures
Descriptor table
brk pointer

stack 2

Thread 2 context:
Data registers
Condition codes
SP2
PC2

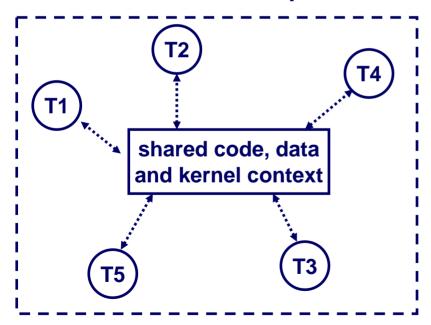


Logical View of Threads

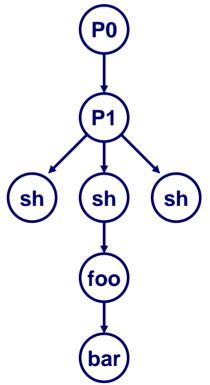
Threads associated with process form a pool of peers.

Unlike processes which form a tree hierarchy

Threads associated with process foo



Process hierarchy



Concurrent Thread Execution

Two threads run concurrently (are concurrent) if their logical flows overlap in time.

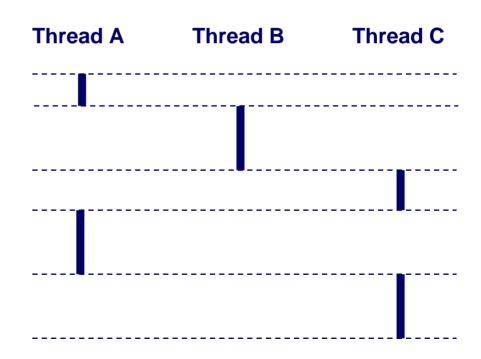
Otherwise, they are sequential.

Examples:

■ Concurrent: A & B, A&C

Sequential: B & C

Time



Threads vs. Processes

How threads and processes are similar

- Each has its own logical control flow.
- Each can run concurrently.
- Each is context switched.

How threads and processes are different

- Threads share code and data, processes (typically) do not.
- Threads are somewhat less expensive than processes.
 - Process control (creating and reaping) is twice as expensive as thread control.
 - Linux/Pentium III numbers:
 - » ~20K cycles to create and reap a process.
 - » ~10K cycles to create and reap a thread.

Posix Threads (Pthreads) Interface

Pthreads: Standard interface for ~60 functions that manipulate threads from C programs.

- Creating and reaping threads.
 - pthread_create
 - pthread_join
- Determining your thread ID
 - pthread_self
- Terminating threads
 - pthread_cancel
 - pthread_exit
 - exit [terminates all threads], ret [terminates current thread]
- Synchronizing access to shared variables
 - pthread_mutex_init
 - pthread_mutex_[un]lock
 - pthread_cond_init
 - pthread_cond_[timed]wait



The Pthreads "hello, world" Program

```
/*
 * hello.c - Pthreads "hello, world" program
                                                     Thread attributes
#include "csapp.h"
                                                      (usually NULL)
void *thread(void *vargp);
                                                     Thread arguments
int main() {
                                                         (void *p)
  pthread t tid;
  Pthread create(&tid, NULL, thread, NULL);
  Pthread join(tid, NULL);
  exit(0);
                                                     return value
                                                      (void **p)
/* thread routine */
void *thread(void *vargp) {
  printf("Hello, world!\n");
  return NULL;
```

Execution of Threaded"hello, world"

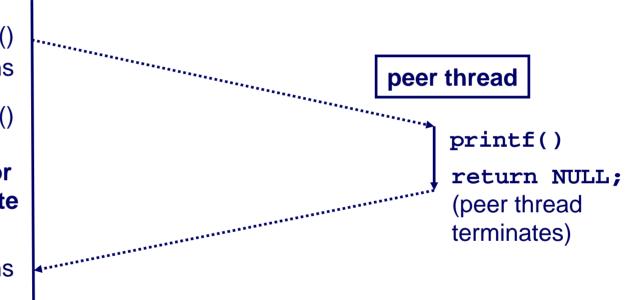
main thread

call Pthread_create()
Pthread_create() returns
call Pthread_join()

main thread waits for peer thread to terminate

Pthread_join() returns

exit()
terminates
main thread and
any peer threads



Thread-Based Concurrent Echo Server

```
int main(int argc, char **argv)
    int port = atoi(argv[1]);
    struct sockaddr in clientaddr;
    int clientlen=sizeof(clientaddr);
   pthread t tid;
    int listenfd = Open listenfd(port);
   while (1) {
       int *connfdp = Malloc(sizeof(int));
       *connfdp = Accept(listenfd, (SA *) &clientaddr, &clientlen);
       Pthread create(&tid, NULL, echo thread, connfdp);
```

- Spawn new thread for each client
- Pass it copy of connection file descriptor
- Note use of Malloc!
 - Without corresponding free

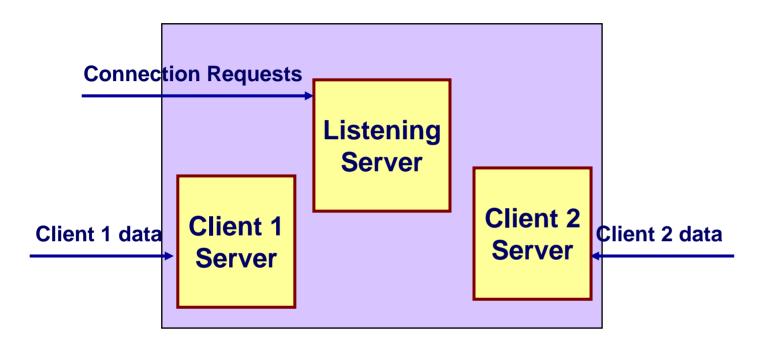


Thread-Based Concurrent Server (cont)

```
/* thread routine */
void *echo_thread(void *vargp)
{
   int connfd = *((int *)vargp);
   Pthread_detach(pthread_self());
   Free(vargp);
   echo(connfd);
   Close(connfd);
   return NULL;
}
```

- Run thread in "detached" mode
 - Runs independently of other threads
 - Reaped when it terminates
- Free storage allocated to hold clientfd
 - "Producer-Consumer" model

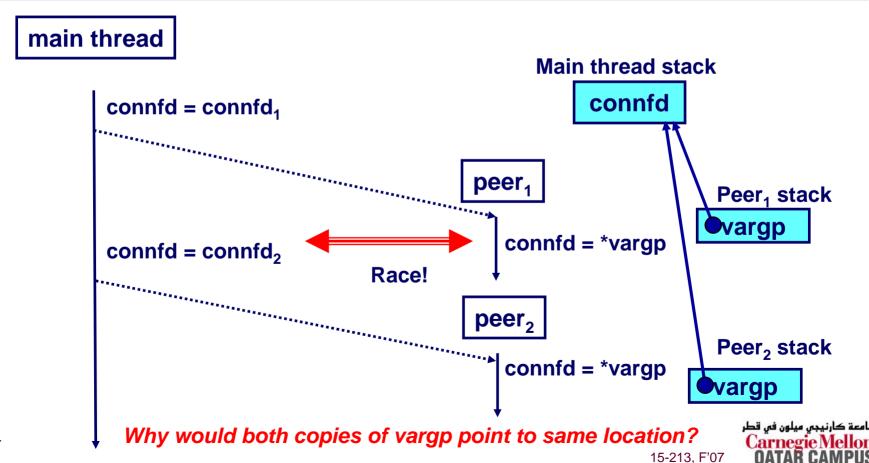
Process Execution Model



- Multiple threads within single process
- Some state between them
 - File descriptors

Potential Form of Unintended Sharing

```
while (1) {
    int connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
    Pthread_create(&tid, NULL, echo_thread, (void *) &connfd);
   }
}
```



Issues With Thread-Based Servers

Must run "detached" to avoid memory leak.

- At any point in time, a thread is either *joinable* or *detached*.
- Joinable thread can be reaped and killed by other threads.
 - must be reaped (with pthread_join) to free memory resources.
- Detached thread cannot be reaped or killed by other threads.
 - resources are automatically reaped on termination.
- Default state is joinable.
 - use pthread_detach(pthread_self()) to make detached.

Must be careful to avoid unintended sharing.

- For example, what happens if we pass the address of connfd to the thread routine?
 - Pthread_create(&tid, NULL, thread, (void
 *)&connfd);

All functions called by a thread must be thread-safe

(next lecture)



Pros and Cons of Thread-Based Designs

- + Easy to share data structures between threads
 - e.g., logging information, file cache.
- + Threads are more efficient than processes.

- --- Unintentional sharing can introduce subtle and hardto-reproduce errors!
 - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads.
 - (next lecture)

Event-Based Concurrent Servers Using I/O Multiplexing

Maintain a pool of connected descriptors.

Repeat the following forever:

- Use the Unix select function to block until:
 - (a) New connection request arrives on the listening descriptor.
 - (b) New data arrives on an existing connected descriptor.
- If (a), add the new connection to the pool of connections.
- If (b), read any available data from the connection
 - Close connection on EOF and remove it from the pool.

The select Function

select() sleeps until one or more file descriptors in the set readset ready for reading.

```
#include <sys/select.h>
int select(int maxfdp1, fd_set *readset, NULL, NULL, NULL);
```

readset

- Opaque bit vector (max FD_SETSIZE bits) that indicates membership in a descriptor set.
- If bit k is 1, then descriptor k is a member of the descriptor set.

maxfdp1

- Maximum descriptor in descriptor set plus 1.
- Tests descriptors 0, 1, 2, ..., maxfdp1 1 for set membership.

select() returns the number of ready descriptors and sets each bit of readset to indicate the ready status of its corresponding descriptor.

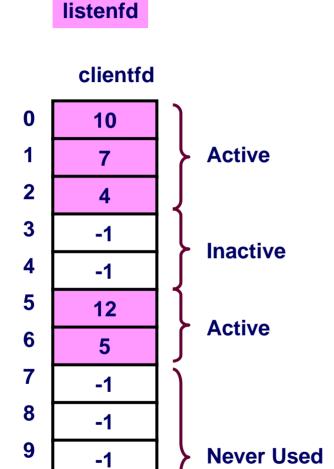
Macros for Manipulating Set Descriptors

```
void FD_ZERO(fd_set *fdset);
    ■ Turn off all bits in fdset.
void FD SET(int fd, fd set *fdset);
    ■ Turn on bit fd in fdset.
void FD CLR(int fd, fd set *fdset);
    ■ Turn off bit fd in fdset.
```

```
int FD_ISSET(int fd, *fdset);
```

Is bit fd in fdset turned on?

Overall Structure



Manage Pool of Connections

- listenfd: Listen for requests from new clients
- Active clients: Ones with a valid connection

Use select to detect activity

- New request on listenfd
- Request by active client

Required Activities

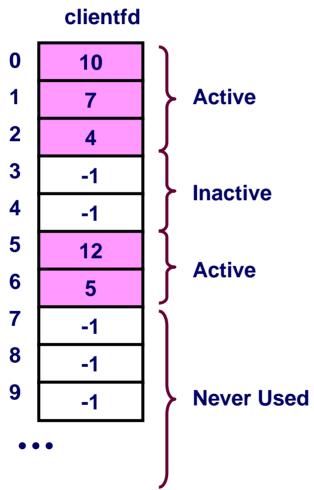
- Adding new clients
- Removing terminated clients
- Echoing

Representing Pool of Clients

```
/*
 * echoservers.c - A concurrent echo server based on select
#include "csapp.h"
typedef struct { /* represents a pool of connected descriptors */
   fd set read set; /* set of all active descriptors */
   fd set ready set; /* subset of descriptors ready for reading */
   int nready; /* number of ready descriptors from select */
   int maxi; /* highwater index into client array */
   int clientfd[FD SETSIZE]; /* set of active descriptors */
   rio t clientrio[FD SETSIZE]; /* set of active read buffers */
} pool;
int byte cnt = 0; /* counts total bytes received by server */
```

Pool Example

listenfd = 3



- maxfd = 12
- maxi = 6
- read_set = { 3, 4, 5, 7, 10, 12 }

Main Loop

```
int main(int argc, char **argv)
    int listenfd, connfd, clientlen = sizeof(struct sockaddr in);
    struct sockaddr in clientaddr;
    static pool pool;
    listenfd = Open listenfd(argv[1]);
    init pool(listenfd, &pool);
   while (1) {
        pool.ready set = pool.read set;
        pool.nready = Select(pool.maxfd+1, &pool.ready set,
                             NULL, NULL, NULL);
        if (FD_ISSET(listenfd, &pool.ready_set)) {
            connfd = Accept(listenfd, (SA *)&clientaddr,&clientlen);
            add client(connfd, &pool);
        check clients(&pool);
```

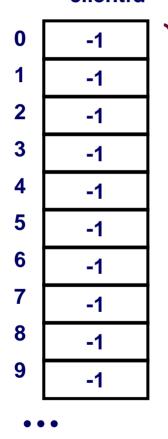
Pool Initialization

```
/* initialize the descriptor pool */
void init pool(int listenfd, pool *p)
    /* Initially, there are no connected descriptors */
    int i;
    p->maxi = -1;
    for (i=0; i< FD SETSIZE; i++)</pre>
        p->clientfd[i] = -1;
    /* Initially, listenfd is only member of select read set */
    p->maxfd = listenfd;
    FD_ZERO(&p->read_set);
    FD SET(listenfd, &p->read set);
```

Initial Pool

listenfd = 3

clientfd



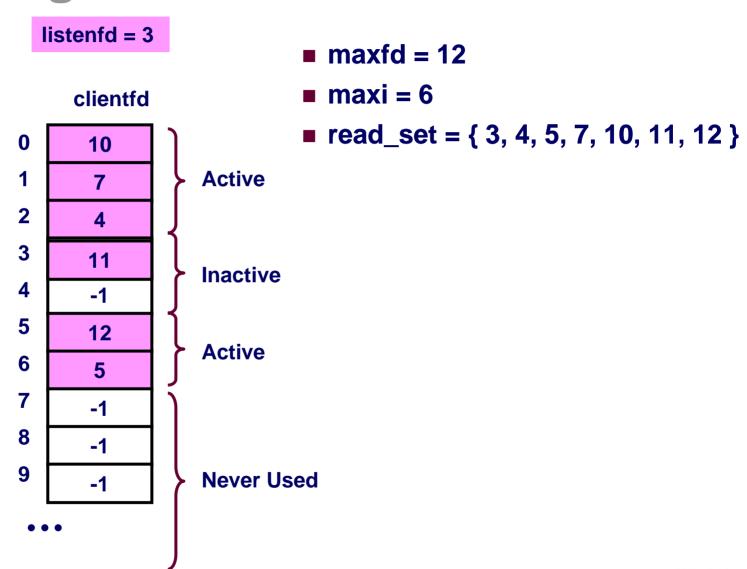
- maxfd = 3
- maxi = -1
- read_set = { 3 }

Never Used

Adding Client

```
void add client(int connfd, pool *p) /* add connfd to pool p */
    int i;
   p->nready--;
   for (i = 0; i < FD SETSIZE; i++) /* Find available slot */
        if (p->clientfd[i] < 0) {</pre>
            p->clientfd[i] = connfd;
            Rio readinitb(&p->clientrio[i], connfd);
            FD SET(connfd, &p->read set); /* Add desc to read set */
            if (connfd > p->maxfd) /* Update max descriptor num */
                p->maxfd = connfd;
            if (i > p->maxi) /* Update pool high water mark */
                p->maxi = i;
            break;
    if (i == FD SETSIZE) /* Couldn't find an empty slot */
        app error("add client error: Too many clients");
```

Adding Client with fd 11



Checking Clients

```
void check_clients(pool *p) { /* echo line from ready descs in pool p */
    int i, connfd, n;
    char buf[MAXLINE];
    rio t rio;
    for (i = 0; (i \le p - \max i) && (p - nready > 0); i++) {
        connfd = p->clientfd[i];
        rio = p->clientrio[i];
        /* If the descriptor is ready, echo a text line from it */
        if ((connfd > 0) && (FD ISSET(connfd, &p->ready set))) {
            p->nready--;
            if ((n = Rio readlineb(&rio, buf, MAXLINE)) != 0) {
                byte cnt += n;
                Rio writen(connfd, buf, n);
            else {/* EOF detected, remove descriptor from pool */
                Close(connfd);
                FD CLR(connfd, &p->read set);
                p->clientfd[i] = -1;
```

Concurrency Limitations

```
if ((connfd > 0) && (FD_ISSET(connfd, &p->ready_set))) {
    p->nready--;
    if ((n = Rio_readlineb(&rio, buf, MAXLINE)) != 0) {
        byte_cnt += n;
        Rio_writen(connfd, buf, n);
    }
}
```

Does not return until complete line received

- Current design will hang up if partial line transmitted
- Bad to have network code that can hang up if client does something weird
 - By mistake or maliciously
- Would require more work to implement more robust version
 - Must allow each read to return only part of line, and reassemble lines within server

Pro and Cons of Event-Based Designs

- + One logical control flow.
- + Can single-step with a debugger.
- + No process or thread control overhead.
 - Design of choice for high-performance Web servers and search engines.
- Significantly more complex to code than process- or thread-based designs.
- Hard to provide fine-grained concurrency
 - E.g., our example will hang up with partial lines.

Approaches to Concurrency

Processes

- Hard to share resources: Easy to avoid unintended sharing
- High overhead in adding/removing clients

Threads

- Easy to share resources: Perhaps too easy
- Medium overhead
- Not much control over scheduling policies
- Difficult to debug
 - Event orderings not repeatable

I/O Multiplexing

- Tedious and low level
- Total control over scheduling
- Very low overhead
- Cannot create as fine grained a level of concurrency

