15-213

Dynamic Memory Allocation I October 20, 2008

Topics

- Simple explicit allocators
 - Data structures
 - Mechanisms
 - Policies



class17.ppt

Harsh Reality

Memory Matters

- Memory is not unbounded
 - It must be allocated and managed
 - Many applications are memory dominated
 - Especially those based on complex, graph algorithms

Memory referencing bugs especially pernicious

- Effects are distant in both time and space
- Memory performance is not uniform
 - Cache and virtual memory effects can greatly affect program performance
 - Adapting program to characteristics of memory system can lead to major speed improvements





Application

Dynamic Memory Allocator

Heap Memory

Explicit vs. Implicit Memory Allocator

- Explicit: application allocates and frees space
 - E.g., malloc and free in C
- Implicit: application allocates, but does not free space
 - E.g. garbage collection in Java, ML or Lisp

Allocation

- In both cases the memory allocator provides an abstraction of memory as a set of blocks
- Doles out free memory blocks to application

Will discuss simple explicit memory allocation today



Process Memory Image

memory invisible kernel virtual memory to user code stack %esp Memory mapped region for shared libraries **Allocators request** additional heap memory from the operating system using the sbrk the "brk" ptr function. run-time heap (via malloc) uninitialized data (.bss) initialized data (.data) program text (.text) بة کارنیدی میلوں فی قطر **Carnegie Mellon** Oatar - 4 -

Malloc Package

#include <stdlib.h>

- void *malloc(size_t size)
 - If successful:
 - Returns a pointer to a memory block of at least size bytes, (typically) aligned to 8-byte boundary.
 - If size == 0, returns NULL
 - If unsuccessful: returns NULL (0) and sets errno.
- void free(void *p)
 - Returns the block pointed at by p to pool of available memory
 - p must come from a previous call to malloc or realloc.
- void *realloc(void *p, size_t size)
 - Changes size of block p and returns pointer to new block.
 - Contents of new block unchanged up to min of old and new size.



Malloc Example

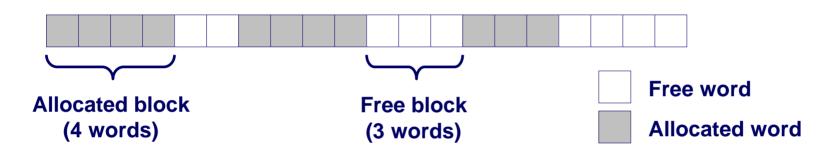
```
void foo(int n, int m) {
  int i, *p;
  /* allocate a block of n ints */
  p = (int *)malloc(n * sizeof(int));
   if (p == NULL) {
   perror("malloc");
   exit(0);
  }
  for (i=0; i<n; i++) p[i] = i;
  /* add m bytes to end of p block */
  if ((p = (int *) realloc(p, (n+m) * sizeof(int))) == NULL) {
   perror("realloc");
   exit(0);
  }
  for (i=n; i < n+m; i++) p[i] = i;
  /* print new array */
  for (i=0; i<n+m; i++)</pre>
   printf("%d\n", p[i]);
  free(p); /* return p to available memory pool */
```

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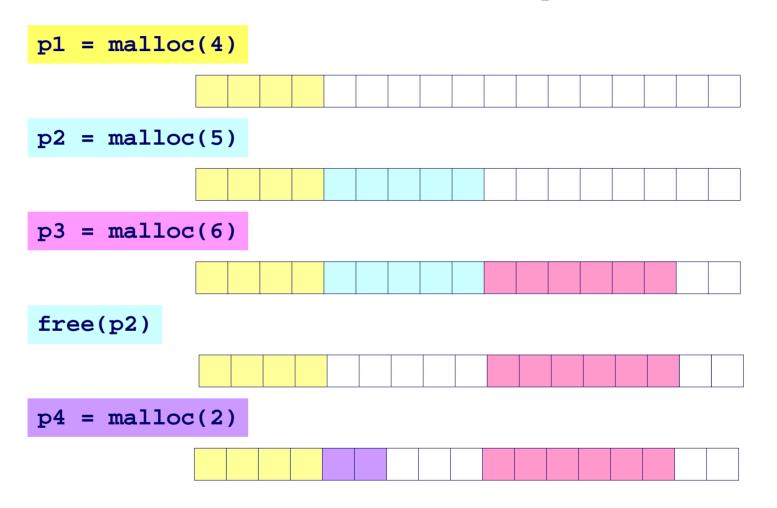
Assumptions made in this lecture

Memory is word addressed (each word can hold a pointer)





Allocation Examples







Applications:

- Can issue arbitrary sequence of allocation and free requests
- Free requests must correspond to an allocated block

Allocators

- Can't control number or size of allocated blocks
- Must respond immediately to all allocation requests
 - *i.e.*, can't reorder or buffer requests
- Must allocate blocks from free memory
 - i.e., can only place allocated blocks in free memory
- Must align blocks so they satisfy all alignment requirements
 8 byte alignment for GNU malloc (libc malloc) on Linux boxes
- Can only manipulate and modify free memory
- Can't move the allocated blocks once they are allocated
 i.e., compaction is not allowed



Performance Goals: Throughput

Given some sequence of malloc and free requests:

 $\blacksquare \ R_0, R_1, ..., R_k, ..., R_{n-1}$

Want to maximize throughput and peak memory utilization.

These goals are often conflicting

Throughput:

- Number of completed requests per unit time
- Example:
 - 5,000 malloc calls and 5,000 free calls in 10 seconds
 - Throughput is 1,000 operations/second.



Performance Goals: Peak Memory Utilization

Given some sequence of malloc and free requests:

 $\blacksquare \ R_0, R_1, ..., R_k, ..., R_{n-1}$

Def: Aggregate payload P_k:

- malloc(p) results in a block with a payload of p bytes.
- After request R_k has completed, the aggregate payload P_k is the sum of currently allocated payloads.

Def: Current heap size is denoted by H_k

- Assume that H_k is monotonically nondecreasing
- Def: Peak memory utilization:
 - After *k* requests, *peak memory utilization* is:
 - $U_k = (max_{i < k} P_i) / H_k$



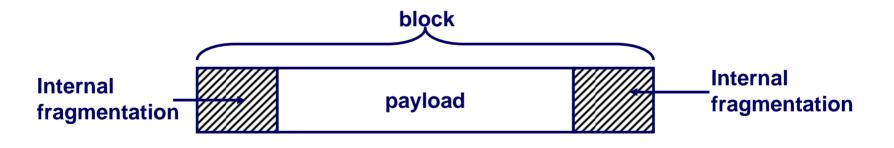
Internal Fragmentation

Poor memory utilization caused by *fragmentation*.

• Comes in two forms: *internal* and *external* fragmentation

Internal fragmentation

For some block, internal fragmentation is the difference between the block size and the payload size.



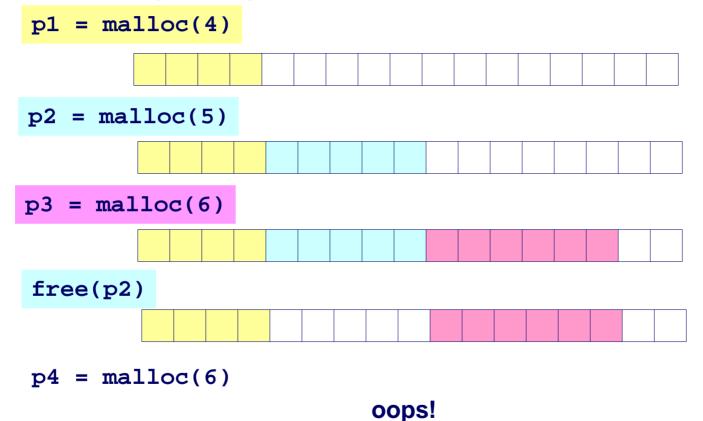
- Caused by overhead of maintaining heap data structures, padding for alignment purposes, or explicit policy decisions (e.g., not to split the block).
- Depends only on the pattern of previous requests, and thus is easy to measure.

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External Fragmentation

Occurs when there is enough aggregate heap memory, but no single free block is large enough



External fragmentation depends on the pattern of *future* requests, and thus is difficult to measure.



Implementation Issues

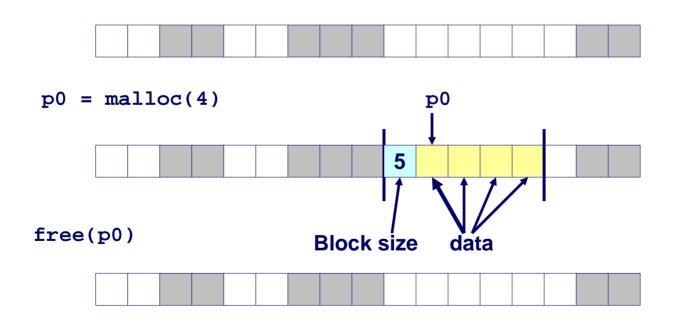
- How do we know how much memory to free just given a pointer?
- How do we keep track of the free blocks?
- What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in?
- How do we pick a block to use for allocation -- many might fit?
- How do we reinsert freed block?



Knowing How Much to Free

Standard method

- Keep the length of a block in the word preceding the block.
 This word is often called the *header field* or *header*
- Requires an extra word for every allocated block



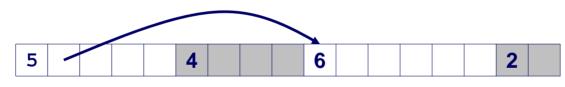




<u>Method 1</u>: <u>Implicit list</u> using lengths -- links all blocks



<u>Method 2</u>: Explicit list among the free blocks using pointers within the free blocks



Method 3: Segregated free list

Different free lists for different size classes

<u>Method 4</u>: Blocks sorted by size

Can use a balanced tree (e.g. Red-Black tree) with pointers within each free block, and the length used as a key

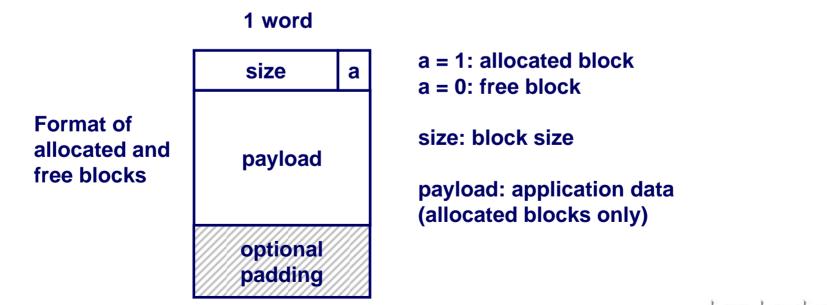


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Method 1: Implicit List

Need to identify whether each block is free or allocated

- Can use extra bit
- Bit can be put in the same word as the size if block sizes are always multiples of two (mask out low order bit when reading size).



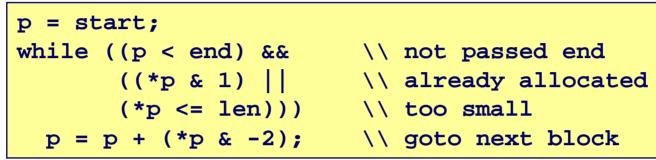
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Implicit List: Finding a Free Block

First fit:

Search list from beginning, choose first free block that fits



- Can take linear time in total number of blocks (allocated and free)
- In practice it can cause "splinters" at beginning of list

Next fit:

- Like first-fit, but search list from location of end of previous search
- Research suggests that fragmentation is worse

Best fit:

- Search the list, choose the free block with the closest size that fits
- Keeps fragments small --- usually helps fragmentation
- Will typically run slower than first-fit





How to represent the Header:

Masks and bitwise operators
 #define SIZEMASK (~0x7)
 #define PACK(size, alloc) ((size) | (alloc))
 #define GET_SIZE(p) ((p)->size & SIZEMASK)

Bitfields

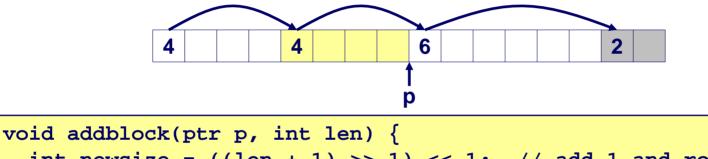
struct {
 unsigned allocated:1;
 unsigned size:31;
} Header;

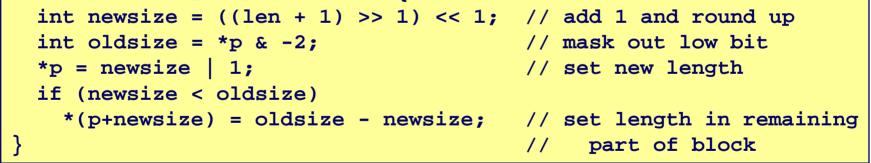


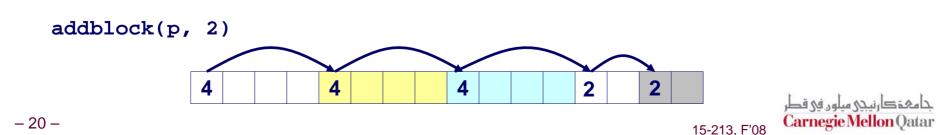
Implicit List: Allocating in Free Block

Allocating in a free block - splitting

Since allocated space might be smaller than free space, we might want to split the block







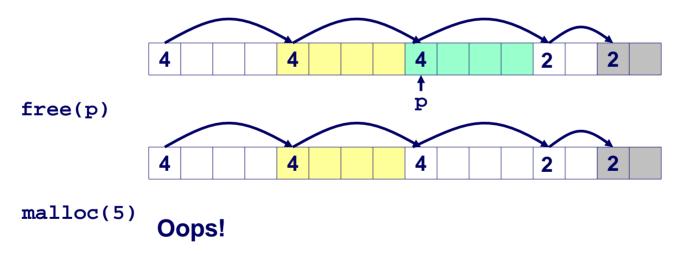
Implicit List: Freeing a Block

Simplest implementation:

Only need to clear allocated flag

void free_block(ptr p) { *p = *p & -2}

But can lead to "false fragmentation"



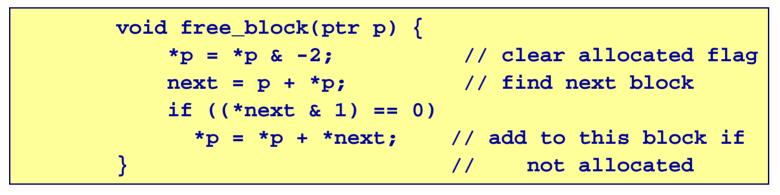
There is enough free space, but the allocator won't be able to find it

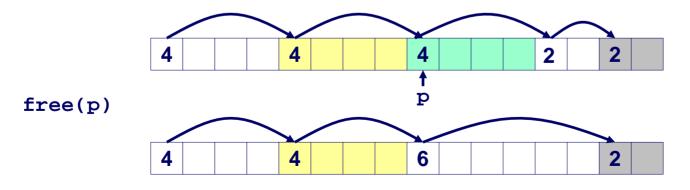


Implicit List: Coalescing

Join (coalesce) with next and/or previous block if they are free

Coalescing with next block



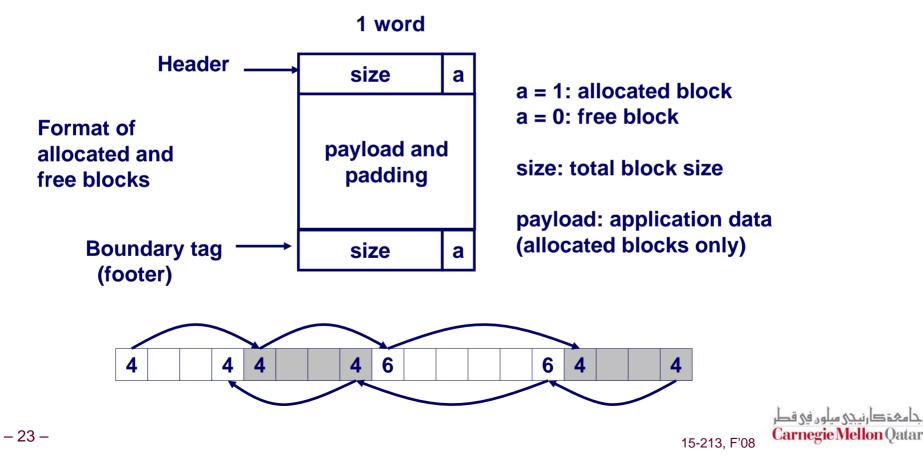


But how do we coalesce with previous block وي المحتاط المحتاط

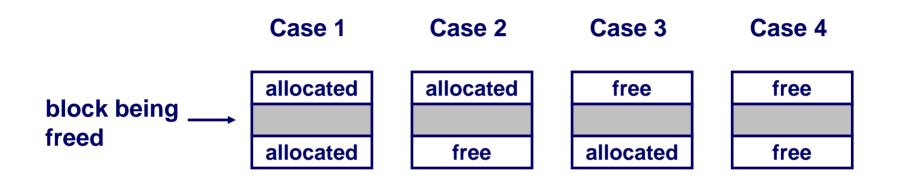
Implicit List: Bidirectional Coalescing

Boundary tags [Knuth73]

- Replicate size/allocated word at bottom of free blocks
- Allows us to traverse the "list" backwards, but requires extra space
- Important and general technique!



Constant Time Coalescing

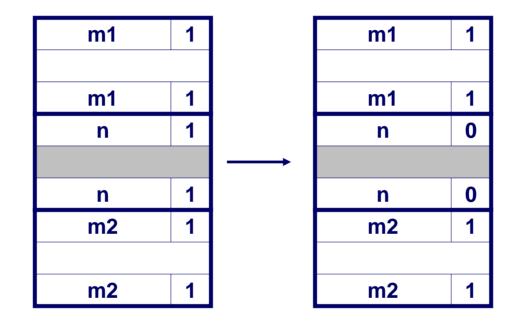




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Constant Time Coalescing (Case 1)

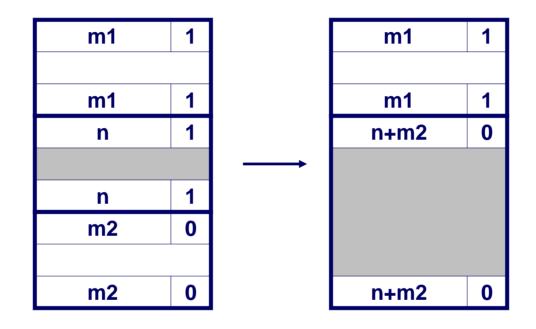




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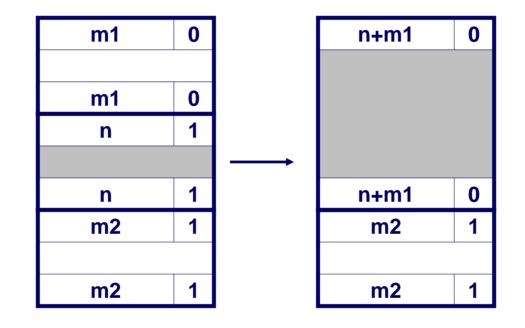
Constant Time Coalescing (Case 2)





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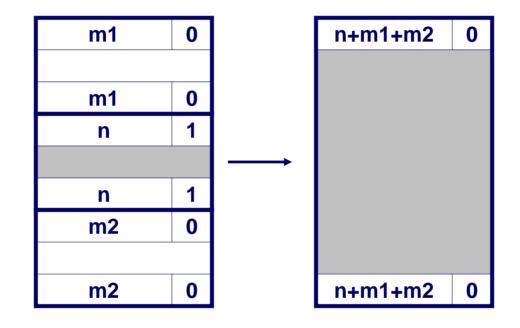
Constant Time Coalescing (Case 3)





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Constant Time Coalescing (Case 4)





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Summary of Key Allocator Policies

Placement policy:

First fit, next fit, best fit, etc.

Trades off lower throughput for less fragmentation

• Interesting observation: segregated free lists (next lecture) approximate a best fit placement policy without having to search entire free list.

Splitting policy:

- When do we go ahead and split free blocks?
- How much internal fragmentation are we willing to tolerate?

Coalescing policy:

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- Immediate coalescing: coalesce each time free is called
- Deferred coalescing: try to improve performance of free by deferring coalescing until needed. e.g.,
 - Coalesce as you scan the free list for malloc.
 - Coalesce when the amount of external fragmentation reaches some threshold.
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Implicit Lists: Summary

- Implementation: very simple
- Allocate cost: linear time worst case
- Free cost: constant time worst case -- even with coalescing
- Memory usage: will depend on placement policy
 First fit, next fit or best fit

Not used in practice for malloc/free because of linear time allocate. Used in many special purpose applications.

However, the concepts of splitting and boundary tag coalescing are general to *all* allocators.

