

15-440: Distributed Systems

Problem Solving Assignment 3

School of Computer Science
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Due date: November 19, 2012

1. Use **Amdahl's law** to resolve the following questions:
 - Suppose a computer program has a method ***M*** that cannot be parallelized, and that this method accounts for 10% of the original program's computation. What is the maximum speed-up of the program on 10 processors vs. on 1000 processors?
 - Suppose that you want to achieve a speedup of 20 with 32 processors. What fraction of the original computation can be sequential?
 - Suppose the method ***M*** accounts for 0.5% of the original program's computation.
 - What will be the maximum speed-up ratio on an unlimited number of processors?
 - What observation can you make regarding obtaining a high degree of scalability?
2. Read the paper entitled "***MapReduce: Simplified Data Processing on Large Clusters***" by Jeffrey Dean and Sanjay Ghemawat and answer the following questions:
 - Summarize the paper in 2 paragraphs.
 - What kind of constraints does MapReduce place on its problem domain? Said in another way, what applications you think would not work (well) in MapReduce?
 - Given the following characteristics of a reliable distributed system: (1) fault-tolerant, (2) highly available, (3) recoverable, (4) consistent, (5) scalable, and (6) predictable performance. For each of these, write a few sentences describing how MapReduce has been designed to exhibit that specific characteristic.
3. The major flaw in the protocol we discussed for installing a next view G_{i+1} in a virtually synchronous reliable multicast is that it cannot deal with process failures while a new view change is being announced. In particular, the protocol assumes that until the new view G_{i+1} has been installed by each member in G_{i+1} , no process in G_{i+1} will fail. Adapt the protocol so that it can tolerate process failures during installing a new view.

4. In the original two-phase commit protocol (2PC) it might be possible that *all* participants block until the coordinator recovers. In this case, participants cannot cooperatively decide on the final action to take. For this reason, 2PC is also referred to as a **blocking commit protocol**.
 - Describe when such a scenario might occur.
 - Describe of whether it is possible to completely eliminate blocking in 2PC, assuming that participants can elect a new coordinator.
 - Can you suggest an adaptation to 2PC to allow participants to reach a final decision, even if the coordinator has not yet recovered?