15-122: Principles of Imperative Computation, Spring 2020 Written Homework 7

Due on Gradescope: Thursday 12th March, 2020 by 9pm

Name:	
Andrew ID:	
Section:	

This written homework covers amortized analysis and hash tables.

Preparing your Submission You can prepare your submission with any PDF editor that you like. Here are a few that prior-semester students recommended:

- *PDFescape* or *DocHub*, two web-based PDF editors that work from anywhere.
- Preview, the Mac's PDF viewer.
- Acrobat Pro, installed on all non-CS cluster machines, works on many platforms.
- *iAnnotate* works on any iOS and Android mobile device.

There are many more — use whatever works best for you. If you'd rather not edit a PDF, you can always print this homework, write your answers *neatly* by hand, and scan it into a PDF file — *we don't recommend this option*, *though*.

Submitting your Work Once you are done, submit this assignment on Gradescope. *Always check it was correctly uploaded*. You have unlimited submissions.

Question:	1	2	3	4	Total
Points:	2.5	4	4.5	1	12
Score:					

1. Remove Operation For Unbounded Arrays

The uba_add operation adds an element to the end of an unbounded array. Conversely, the uba_rem operation removes the element at the end. (Remember that the "end" of the array is from the client's perspective. There may be additional unused positions in the array from the implementation's perspective.) When removing, we don't need to resize the array to a smaller size, but we could. However, we need to consider *when* to shrink the array in order to guarantee O(1) amortized runtime.

0.5pts

1.1 If the array resizes to be twice as large as soon as it is full (as in lecture), and resizes to be half as large as soon as it is strictly less than half full, give a sequence of additions and removals, starting from a new array A of size 3 (limit 6), that will cause the worst-case behavior. End your solution with "..." after you clearly establish the repeating behavior, and after each operation write the size, limit, and number of array writes for that operation. The first line of the answer is shown.

```
// size = 3, limit = 6
uba_add(A, "y"); // size = 4, limit = 6, 1 array write
```

1pt

1.2 Generalizing, with the strategy above, what is the worst case runtime complexity, using big-O notation, of performing k operations on an array of size n, where each operation is taken from the set {uba_add, uba_rem} ?

O()		

Differently from lecture, this type of amortized analysis involves multiple operations, each costing a different number of tokens possibly. The amortized cost of each operation is found by dividing the total cost by the number of operations. (This is known as "aggregate" analysis.)

Using aggregate analysis, what is the amortized cost of each of the k operations in the worst case?

O()	

1pt

1.3 Instead of resizing the array to be half as large as soon as it is strictly less than half full, we could resize the array to half of its current size when it is *exactly* a quarter full. This will lead to O(1) amortized cost per remove operation. Using an array of size 11 (limit 12), show the effect of an add operation followed by the sequence of remove operations that causes the array to resize. As before, show the size and limit of the array after each operation, and indicate how many array writes each step takes. The first two lines are given for you.

```
// size = 11, limit = 12
uba_add(A, "y");  // size = 12, limit = 24, 13 array writes
uba_rem(A);  // size = 11, limit = 24, 0 array writes
```

In the answer above, the initial uba_add operation doubled the size of the array, consuming every banked tokens. Based on your answer above, what is the minimum number of tokens that should be charged for each uba_rem operation so that enough tokens are banked for the resize of the array? In your analysis, the *only* thing we have to pay for with tokens is array writes.

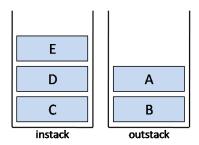
 token(s).

2. A New Implementation of Queues

Recall the interface for a stack that stores elements of the type elem:

For this question you will analyze a different implementation of the queue interface. Instead of a linked list, this implementation uses two stacks, called instack and outstack. To enqueue an element, we push it on top of the instack. To dequeue an element, we pop the top off of the outstack. If the outstack is empty when we try to dequeue, then we will first move all of the elements from the instack to the outstack, then pop the outstack.

For example, below is one possible configuration of a two-stack queue containing the elements A through E (A is at the front and E is at the back of the abstract queue):



We will use the following C0 code:

```
typedef struct stackqueue_header stackqueue;
struct stackqueue_header {
   stack_t instack;
   stack_t outstack;
};

typedef stackqueue* queue_t;
```

```
bool is_stackqueue(stackqueue* Q) {
  return Q != NULL && Q->instack != NULL && Q->outstack != NULL;
}
stackqueue* queue_new()
//@ensures is_stackqueue(\result);
  stackqueue* Q = alloc(stackqueue);
  Q->instack = stack_new();
  0->outstack = stack_new();
  return Q;
}
bool queue_empty(stackqueue* Q)
//@requires is_stackqueue(Q);
//@ensures is_stackqueue(Q);
  return stack_empty(Q->instack) && stack_empty(Q->outstack);
}
void eng(stackqueue* Q, elem x)
//@requires is_stackqueue(Q);
//@ensures is_stackqueue(Q);
{
   push(Q->instack, x);
}
elem deq(stackqueue* Q)
//@requires is_stackqueue(Q);
//@requires !queue_empty(Q);
//@ensures is_stackqueue(Q);
{
    if (stack_empty(Q->outstack)) {
       while (!stack_empty(Q->instack))
         push(Q->outstack, pop(Q->instack));
    return pop(Q->outstack);
}
```

0.5pts

2.1 Given a queue with k elements in it, exactly how many different ways can this queue be represented using two stacks, as a function of k?

way(s).	

1	n	+
T	ν	·ι

2.2 We now determine the runtime complexity of the enq and deq operations. Let k be the total number of elements in the queue.

What is the worst-case runtime complexity of each of the following queue operations based on the description of the data structure implementation given above? Write ONE sentence that explains each answer.

enq: $O($), because
deq: $O($	_), because

2.5pts

2.3 Using amortized analysis, we can show that the worst-case complexity of a *valid* sequence of n enqueue/dequeue operations starting from an empty queue is O(n). This means that the amortized cost per operation is O(1), even though the worst-case cost of an individual operation may not be constant.

Here, a *valid sequence* of queue operations must start with the empty queue, each operation must be either an enq or a deq, and you must have enough tokens. Assume that push and pop each consume one token (and emptiness tests are free).

How many tokens should be charged to enqueue an element? How many to dequeue an element? Your answers should be constant integers — recall that the amortized cost is to be O(1). Justify each answer by briefly stating for what purpose of each token is used (*you may not need all lines*).

Cost of enq:	token(s), to be used as follows:
1 token to _	
1 token to _	
Cost of deq:	token(s), to be used as follows:
	token(s), to be used as follows:
1 token to _	
1 token to _ 1 token to _	
1 token to _ 1 token to _ 1 token to _	

3. Hash Tables: Dealing with Collisions

In a hash table, when two keys hash to the same location, we have a *collision*. There are multiple strategies for handling collisions:

- **Separate chaining**: each location in the table stores a chain (typically a linked list) of all keys that hashed to that location.
- **Open addressing**: each location in the table stores a key directly. In case of a collision when inserting, we *probe* the table to search for an available storage location. Similarly, in case of a collision when looking up a key k, we probe to search for k. Suppose our hash function is k, the size of the table is k, and we are attempting to insert or look up the key k:
 - *Linear probing*: on the i^{th} attempt (counting from 0), we look at index (h(k)+i) mod m.
 - *Quadratic probing*: on the i^{th} attempt (counting from 0), we look at index $(h(k) + i^2) \mod m$.

For insertion, we are searching for an empty slot to put the key in. For lookup, we are trying to find the key itself.

pt	3.1 You are given a hash table of size m with n inserted keys. Collisions are resolved
	using separate chaining. If $n = 2m$ and the keys are <i>not</i> evenly distributed, what
	is the worst-case runtime complexity of searching for a specific key using big-C
	notation?

O()	

Under the same conditions, except that now the keys *are* evenly distributed, what is the worst-case runtime complexity of searching for a specific key using big O notation?

O()	

As usual, for both of the answers above, give the tightest, simplest bound.

For the next three questions, you are given a hash table of capacity m=13. The hash function is h(k)=k; after hashing we attempt to insert the key k at array index h(k) mod m.

1pt

3.2 Assume the table resolves collisions using separate chaining. Show how the set of keys below will be stored in the hash table by drawing the *final* state of each chain of the table after all of the keys are inserted, one by one, in the order shown.

You may insert keys either always at the beginning or always at the end of a chain, but be consistent. Wherever they occur, you should indicate NULL pointers explicitly by the notation from class:

0				
1				
2				
3				
4				
5				
6				
7				
8				
9				
10				
11				
12				

1pt

3.3 Show where the keys in the sequence below are stored in the same hash table if they are inserted one by one, in the order shown, using *linear probing* to resolve collisions.

53, 40, 50, 87, 37, 74, 47, 11

.5pt

3.4 Show where the keys in the sequence below are stored in the same hash table if they are inserted one by one, in the order shown, using *quadratic probing* to resolve collisions.

53, 40, 50, 87, 37, 74, 47, 11

0	1	2	3	4	5	6	7	8	9	10	11	12

1pt

3.5 Quadratic probing suffers from one problem that linear probing does not. Given a non-full hash table, insertions with linear probing will always succeed, while insertions with quadratic probing might not (i.e., they may never find an open spot to insert).

Using h(k) = k as your hash function and m = 6 as your table capacity, give an example of a table with load factor not above 2/3 and a key that cannot be successfully inserted into the table. (*Hint:* start entering different multiples of 6.)

0	1	2	3	4	5

Key that cannot successfully be inserted:

4. Strings as Keys

In a popular programming language, non-empty strings are hashed using the following function:

$$H(s) = (s_0 \times 31^{|s|-1} + s_1 \times 31^{|s|-2} + \dots + s_{|s|-2} \times 31^1 + s_{|s|-1} \times 31^0) \% m$$

where s_i is the ASCII code (http://www.asciitable.com/) for the i^{th} character of string s (starting at 0 and counting from left to right), |s| is the length of s, and m is the size of the hash table. We consider 7-bit ASCII codes, so that each character is encoded as a number between 0 and 127 (included).

0.5pts

4.1 If 15105 strings were stored in a hash table of size 3021 using separate chaining, what would the load factor of the table be? If the strings above were equally distributed in the hash table, what does the load factor tell you about the possible lengths of the chains?

The load factor is
Each chain has length

0.5pts

4.2 Using the hash function above with a table size of 3021, give an example of two different strings that would "collide" in the hash table and would be stored in the same chain. Show your work. (For your own sake, and ours, use strings of up to 2 printable characters.)